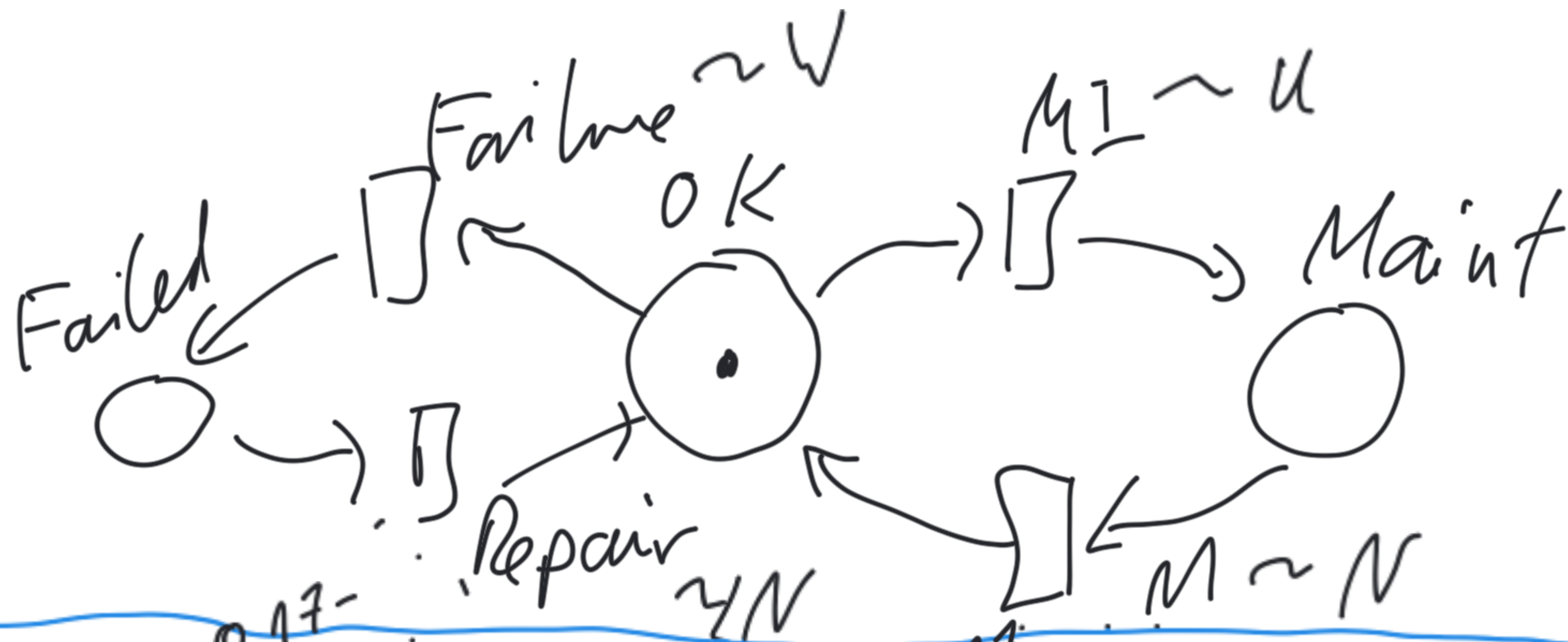
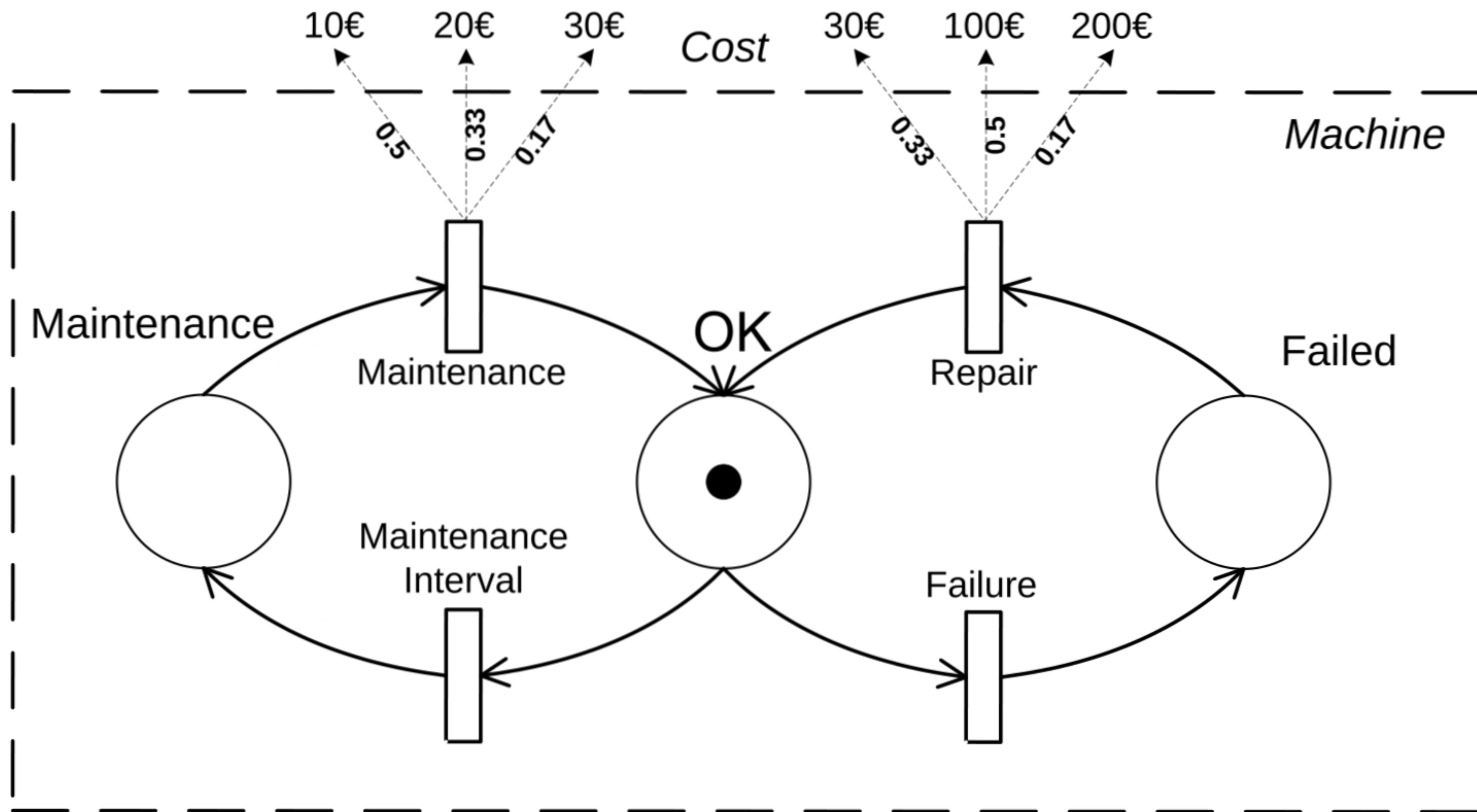


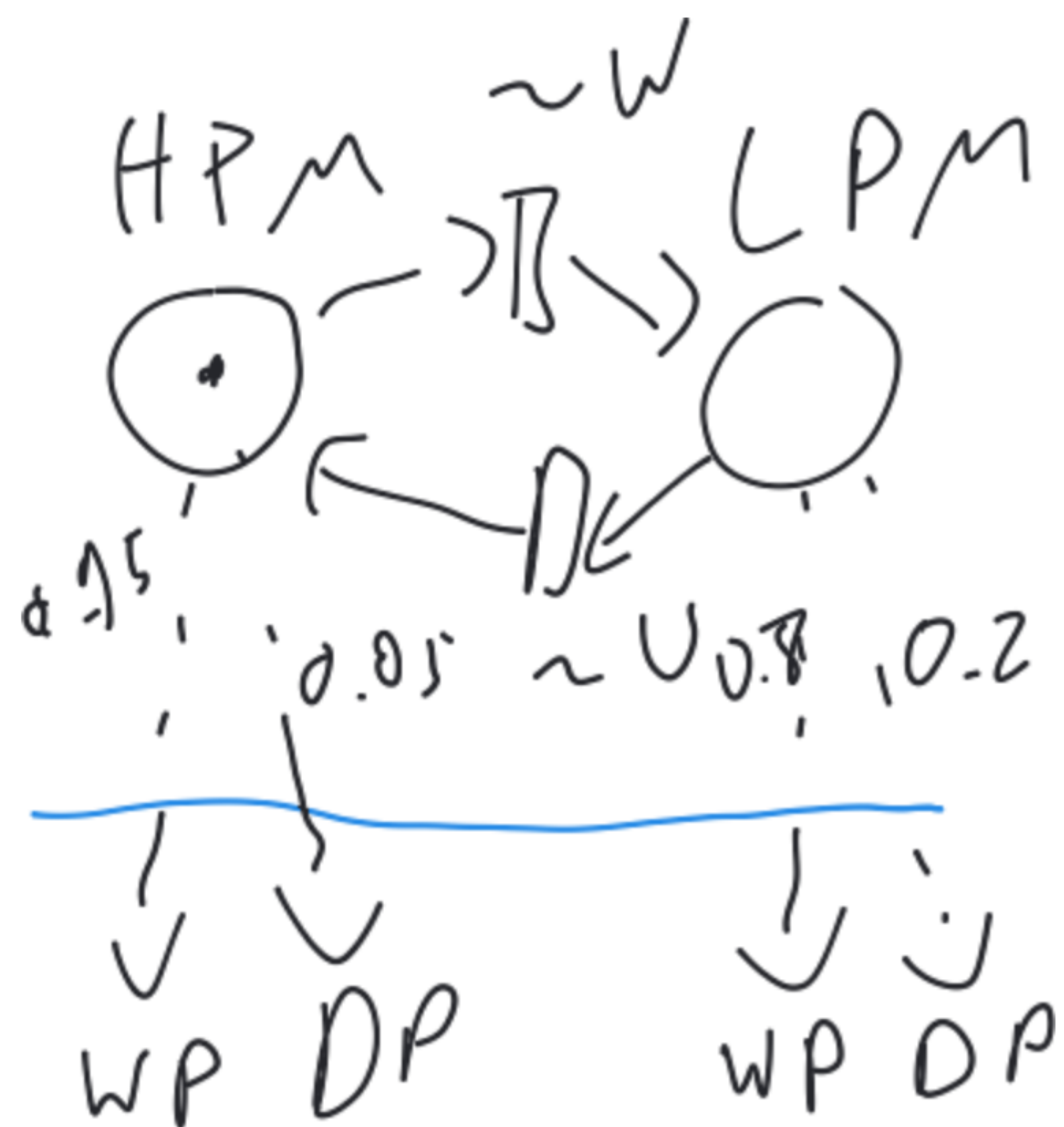
H

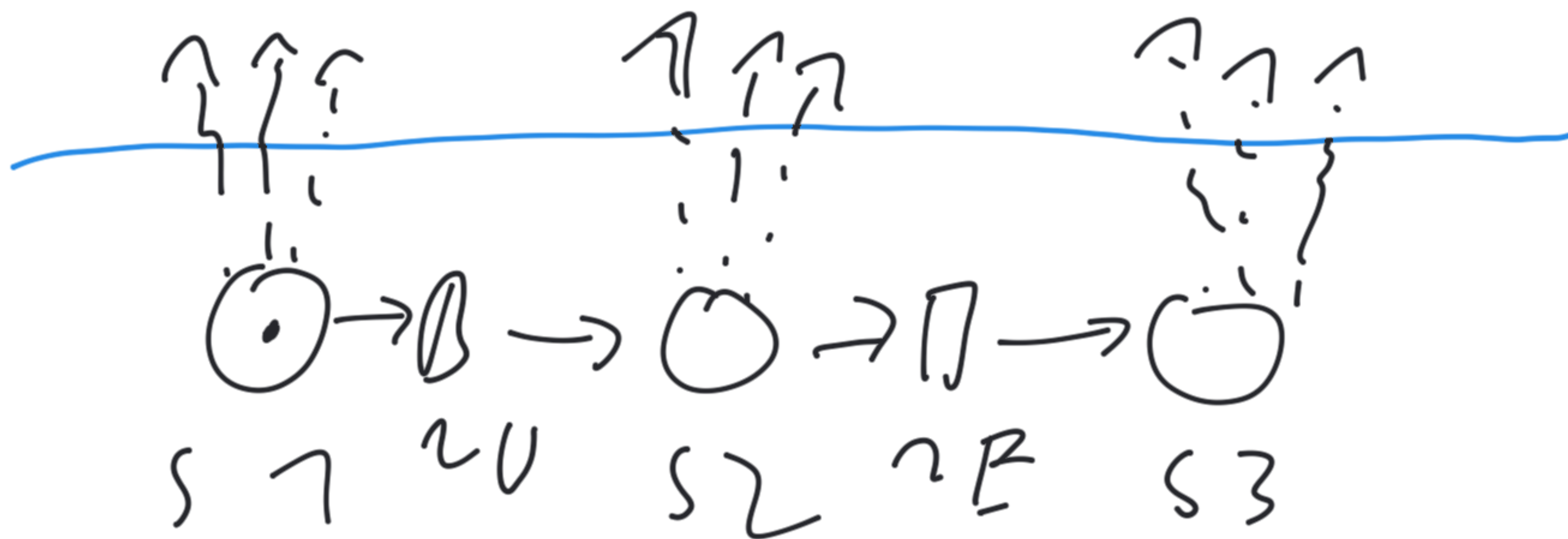


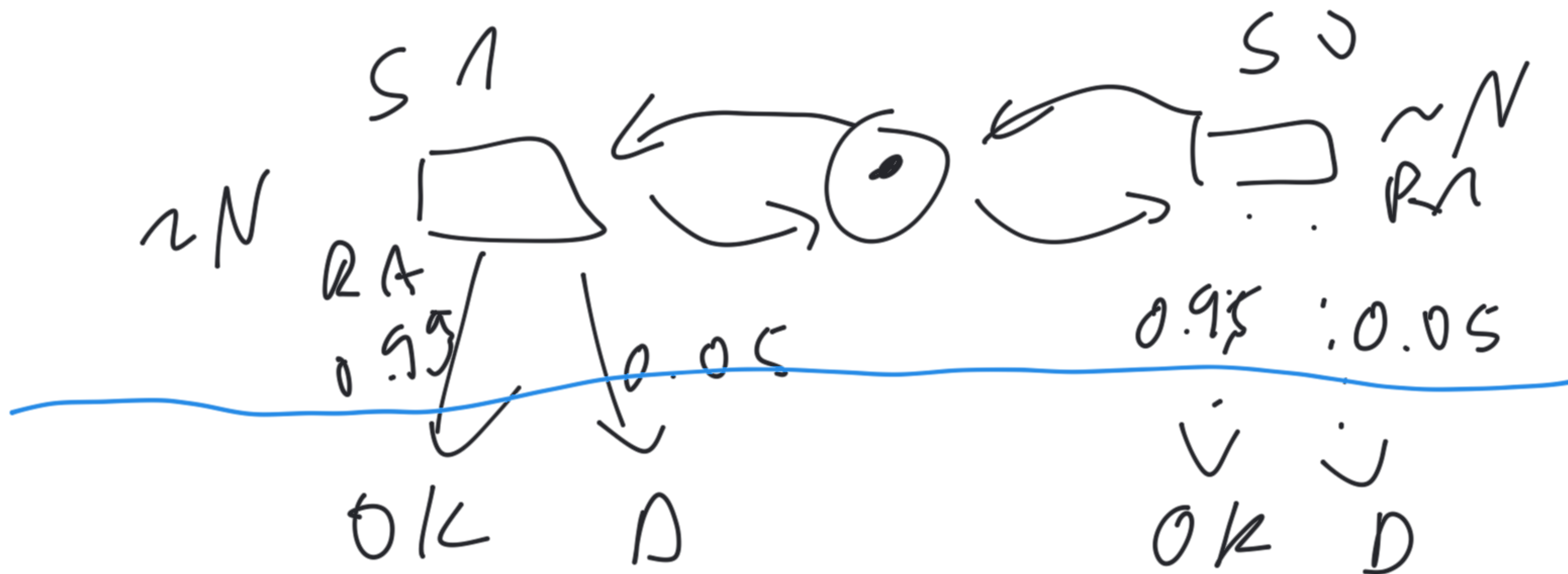
0

0.17 ✓ 0.5 ✓ 0.33 ✓
 200 100 30
 0 = (2; 10) (4; 20)









D S M

comp. obs.

non Mark.

System \rightarrow behavior



protocol data \rightarrow system analysis

H M M

not com. obs.

DTMC

behavior \rightarrow system



Hidden non-Markovian Models

HnMM

- DMM as hidden part
- cont. dist. f.

- emissions \rightarrow trans.

\hookrightarrow ind. sampling

$$\text{FluMM} = (S, V, TR, A, \tau)$$

$$S = \{s_1 \dots s_n\}$$

$$V = \{v_1 \dots v_m\}$$

$$TR = \{TR_1 \dots TR_k\}$$

$$TR_k = (\text{dist}, b(v), \text{aging})$$

$$b(w) : V \rightarrow [0, 1]$$

$$A = \{a_{ij}\}_{n \times n} \quad a_{ij} \in TR$$

$$O = \{ (o_1, e_1) \dots (o_\tau, e_\tau) \}$$

$$Q = \{ (q_0, e_0) \dots (q_P, e_P) \}$$

$$P \geq T$$

$$\lambda = \{ A, \pi \}$$

$$ISP : TR = (dist, agt_{tr}) \quad (S, V, TR, A, B, \pi)$$

$$S = \{OK, Maint., Failed\} = \{OK, M, F\}$$

$$V = \{10, 20, 30, 100, 200\}$$

$$TR = \{TR_{MI}, TR_M, TR_F, TR_R\}$$

$$TR_{MI} = (U(a, b), b(v) = 0, \text{false})$$

$$TR_F = (W(\alpha, \beta), b(v) = 0, \text{false})$$

$$TR_M = (N(\mu, \sigma), b(10) = 0.5, b(20) = 0.33, b(30) = 0.17, \text{false})$$

$$TR_R = (LN(\mu, \sigma), b(30) = 0.33, b(100) = 0.5, b(200) = 0.17, \text{false})$$

$$S = \{OK, Maint., Failed\} = \{OK, M, F\}$$

$$V = \{10, 20, 30, 100, 200\}$$

$$TR = (TR_M, TR_M, TR_F, TR_R)$$

$$A = \begin{bmatrix} \emptyset & TR_M & TR_F \\ TR_M & \emptyset & \emptyset \\ TR_R & \emptyset & \emptyset \end{bmatrix}$$

$$\pi = (1, 0, 0)$$

① SC_{oneT} / SC_{nT}

② E_{all} / E_{some}

③ T_{keep} / T_{reset} $\odot \rightarrow \square$

$\odot \rightarrow \square$

$(2, 30)$ $(4, 20)$

